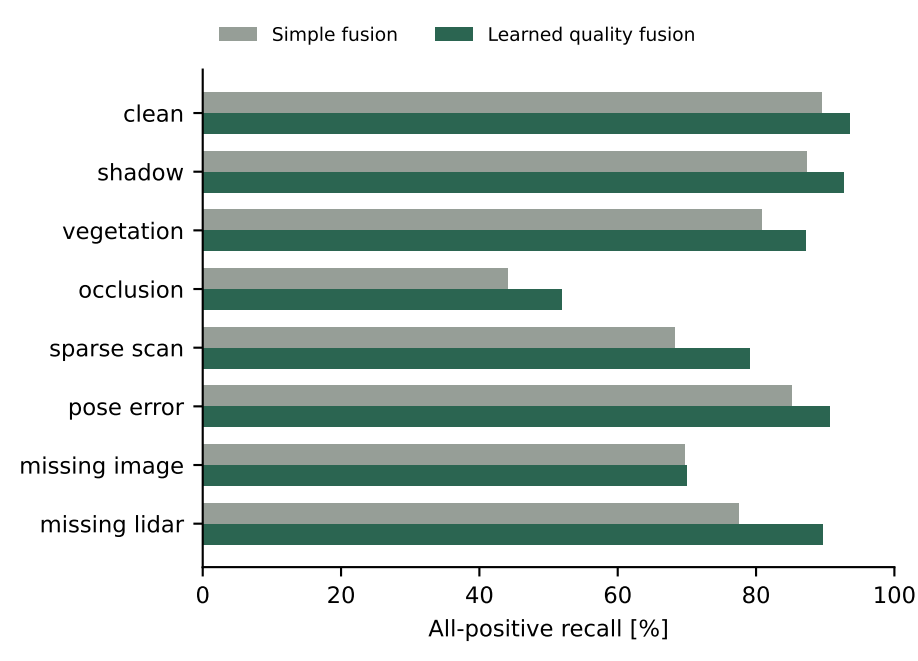
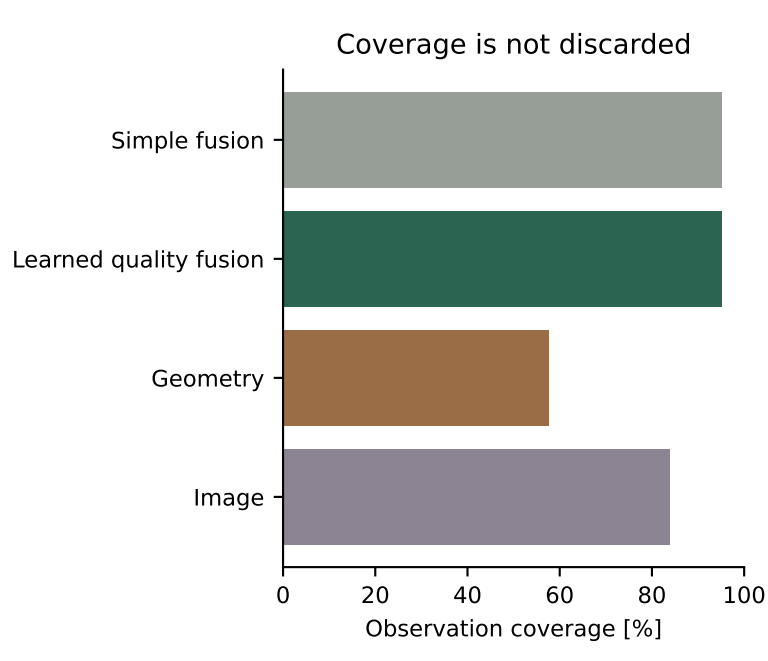

Simple fusion
Learned quality fusion
clean
shadow
vegetation
occlusion
sparse scan
pose error
missing image
missing lidar
0
20
40
60
80
100
All-positive recall [%]


Coverage is not discarded
Simple fusion
Learned quality fusion
Geometry
Image
0
20
40
60
80
100
Observation coverage [%]