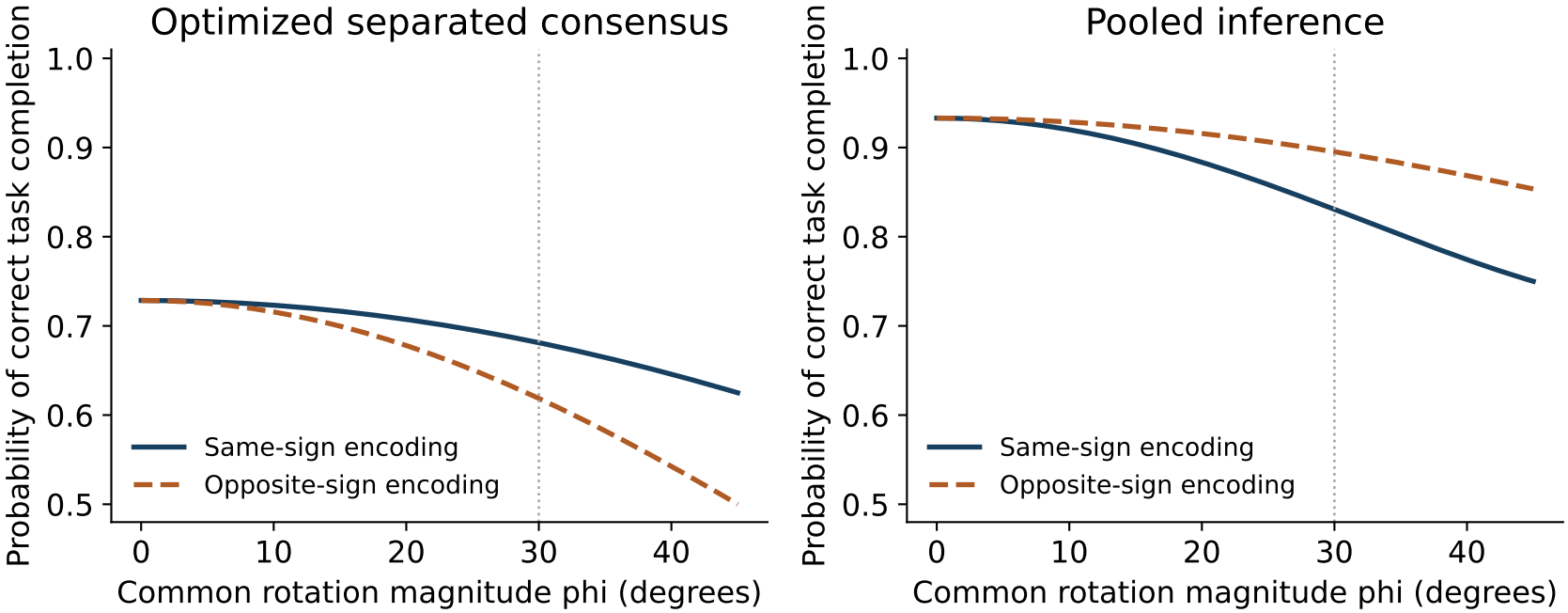
Optimized separated consensus
Pooled inference
Probability of correct task completion
1.0
0.9
0.8
0.7
0.6
0.5
0
10
20
30
40
Common rotation magnitude phi (degrees)
Same-sign encoding
Opposite-sign encoding